## STAT 530: Decision Theory Continued

Feb 3, 2009

### Start with loss function, $L(\theta, a)$ , recall definitions:

- $R(\theta, \delta)$  is **risk function** of rule (estimator)  $\delta()$ :
  - expected value of  $L(\theta, \delta(Y))$ , w.r.t. sampling  $(Y|\theta)$
- $r(\pi, \delta)$  is **Bayes risk** of of  $\delta()$ :
  - $\blacksquare$  average risk w.r.t.  $\theta \sim \pi$
  - think of  $\pi$  as *nature's prior*.
- $\rho_{\pi}(a; y)$  is **posterior risk** of action (estimate) *a*:
  - average of  $L(\theta, a)$  w.r.t. posterior on  $(\theta | Y = y)$

• here think of  $\pi$  as investigator's prior

## Big Fact #1: Choice of loss function influences choice of which Bayesian estimator

General Bayesian principle: 'the' Bayesian estimator is:

$$\delta_B(y) \equiv \operatorname{argmin}_a E\{L(\theta, a)|Y = y\}$$

Examples:

• 
$$L(\theta, a) = (a - \theta)^2$$
 implies  $\delta_B(y) = E(\theta | Y = y)$   
•  $L(\theta, a) = |a - \theta|$  implies  $\delta_B(y) = \text{Median}(\theta | Y = y)$ 

# Big Fact #2: Sense in which Bayes estimators are best possible

The Bayes risk based on nature's prior  $\pi_N$  is minimized - amongst all possible estimation procedures  $\delta()$  - by the Bayes estimator which uses  $\pi_N$  as the investigator's prior.

Proof by changing the order of integration.

### Recall: $\delta()$ inadmissible if there exists $\delta^*()$ such that

 $R(\theta, \delta) \leq R(\theta, \delta^*)$ 

for all  $\theta$ , with strict inequality for at least one  $\theta$ .

And an estimator is admissible if it is not inadmissible.

#### It is *almost* the case that:

 $\delta()$  is admissible  $\leftrightarrow \delta()$  is a Bayes estimator w.r.t. some prior.

## Say $\delta()$ is Bayes estimator w.r.t. $\pi$ , show $\delta()$ admissible

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Look at simple case  $\theta \in \{\theta_1, \theta_2, \ldots\}$ 

Proof by picture in very simple case  $\theta \in \{\theta_1, \theta_2\}$ :

Visualize any  $\delta()$  as point  $(R_1, R_2) = R(\theta_1, \delta), R(\theta_2, \delta)$  in 'risk set'.

- risk set necessarily convex (think of randomized rules)
- 'lower boundary' of the set corresponds to admissible rules

- at any boundary point, convex set 'supported' by a line
- express line as  $\pi_1 R_1 + \pi_2 R_2 = c$
- Voila! rule minimizes Bayes risk w.r.t. this  $\pi$

More precisely, admissible estimators are Bayes estimators plus some 'limits' of Bayes estimators

E.g. 
$$Y \sim N(\theta, 1)$$
,  $L(\theta, a) = (a - \theta)^2$ .

 $\delta(Y) = Y$  is

- admissible
- not the posterior mean arising from any proper prior
- the  $\tau^2 \to \infty$  limit of  $E(\theta|Y = y)$  via the prior  $\theta \sim N(0, \tau^2)$ .

$$Y \sim N_p(\theta, I_p), \ L(\theta, a) = \|a - \theta\|^2$$

### Consider $\delta(Y) = Y$

- p = 1: admissible
- p = 2: admissible
- p >= 3: inadmissible
  - James-Stein (1960)

shocking!

Showed that  $\delta_{JS}(Y) = (1 - (p - 2)/||Y||^2)Y$  beats  $\delta(Y) = Y$ Later, someone showed  $\delta_{JS}()$  is beaten by  $\delta_{JS}^+(Y) = \max\{0, 1 - (p - 2)/||Y||^2)\}Y$ . Later someone showed  $\delta_{JS}^+$  inadmissible, without actually finding an estimator that beats it! Isn't math great?